

# Motor Inverter Compatibility Topics

- ❖ Reflected Wave Theory
- ❖ Waveform Analysis with output reactors & filters
- ❖ Long Motor Leads
- ❖ Drive Solutions
- ❖ Motor Solutions



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# Reflected Wave Theory



## Mismatch between surge impedance of: Drive-to-motor cable & Motor winding

- ❖ Cable surge impedance fairly constant through hp range
- ❖ Motor surge impedance inversely proportional to hp
- ❖ 2 per unit voltage evident on motors up to 500 hp
- ❖ Motor terminal voltage doubling on leads over 15 feet



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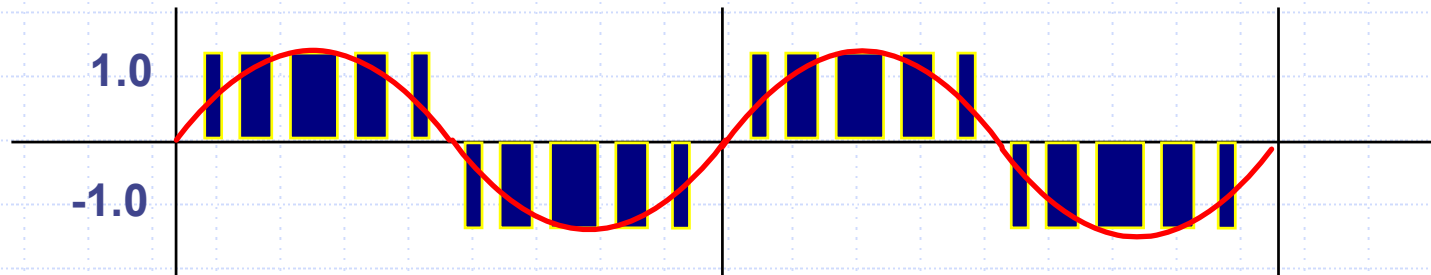
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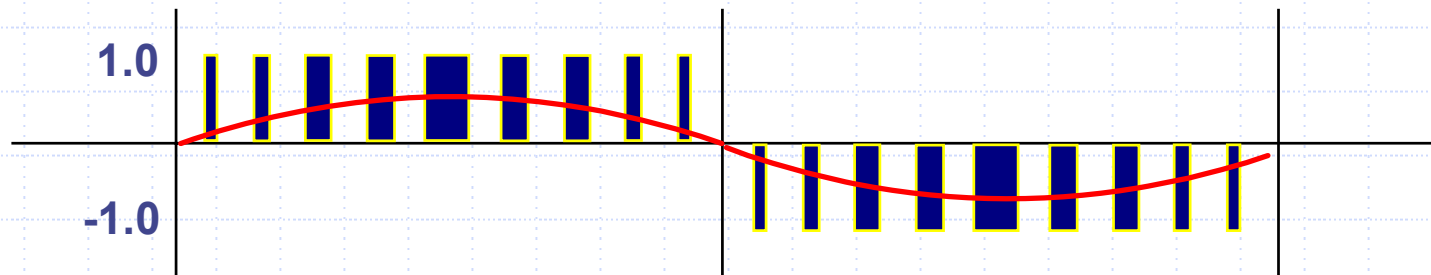
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# PWM Waveform



**Full Voltage, 60 Hz PWM Waveform**



**Half Voltage, 30 Hz PWM Waveform**



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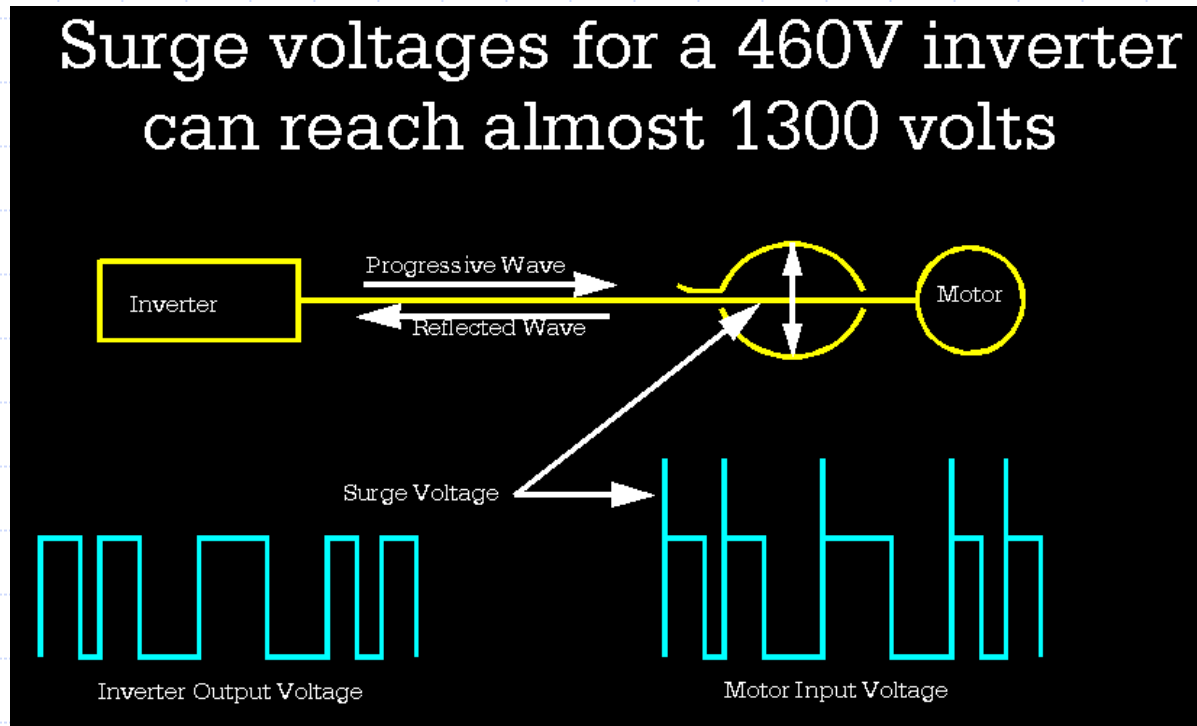
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# VFD Output & Motor Terminal Voltage, Reflected Waves



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# IGBT VFD, Motor Terminal Peak Voltage & Rise Time Characteristics



Peak voltage = twice DC Bus voltage at critical cable length and longer. DC bus voltage = AC input voltage \* 1.414.

e.g. 600 VAC \* 1.414 = 850 \* 2 = 1,700 V Peak.

Rise time = 0.25uS to 1uS Depending on IGBT Current Rating

Critical cable length = speed of propagation \* rise time.

e.g. 150meters/uS \* 0.25uS = 37.5 meters



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# NEMA Minimum Design Standards For 3 Phase Induction Motors



## **MG1 part 30**

As a minimum  
motor insulation  
must withstand

1000 volt peak @  
2uS rise time

## **MG1 part 31**

As a minimum  
motor insulation  
must withstand

1600 volt peak @  
0.1uS rise time



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# VFD Solutions

## For NEMA MG1 part 30 Motors

- ❖ No output reactor or filter required for 208/240Volt applications
- ❖ Use output reactor for 460 volt applications
- ❖ Use output dv/dt filters for 600 volt applications
- ❖ Keep motor leads short
- ❖ Keep carrier frequency low
- ❖ Keep motor cool



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# Motor Solutions

## For NEMA MG1 part 31 Motors

- ❖ No output reactor or filter required for 208/240 volt applications
- ❖ No reactor or output filter required for 460 or 600 volt applications unless cable length is extreme



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